

```

/*-----*/
/* Skeleton 2-1/2D Electromagnetic MPI/OpenMP PIC code */
/* written by Viktor K. Decyk, UCLA */
#include <stdlib.h>
#include <stdio.h>
#include <complex.h>
#include <sys/time.h>
#include "mpbpush2.h"
#include "pplib2.h"
#include "omplib.h"

void dtimer(double *time, struct timeval *itime, int icntrl);

int main(int argc, char *argv[]) {
    int indx = 9, indy = 9;
    int npx = 3072, npy = 3072;
    int ndim = 3;
    float tend = 10.0, dt = 0.04, qme = -1.0;
/* float tend = 10.0, dt = 0.025, qme = -1.0; */
    float vtx = 1.0, vty = 1.0, vx0 = 0.0, vy0 = 0.0;
    float vtz = 1.0, vz0 = 0.0;
    float ax = .912871, ay = .912871, ci = 0.1;
/* idimp = dimension of phase space = 5 */
/* relativity = (no,yes) = (0,1) = relativity is used */
    int idimp = 5, ipbc = 1, relativity = 1;
/* idps = number of partition boundaries */
    int idps = 2;
    float wke = 0.0, we = 0.0, wf = 0.0, wm = 0.0, wt = 0.0;
/* sorting tiles, should be less than or equal to 32 */
    int mx = 16, my = 16;
/* fraction of extra particles needed for particle management */
    float xtras = 0.2;
/* declare scalars for standard code */
    int j;
    int nx, ny, nxh, nyh, nxe, nye, nxeh, nnxe, nxyh, nxhy;
    int mx1, ntime, nloop, isign, ierr;
    float qbme, affp, dth;
    double np;

/* declare scalars for MPI code */
    int ntpose = 1;
    int nvp, idproc, kstrt, npmax, kxp, kyp, nypmx, nypmn;
    int nyp, noff, npp, nps, mypl, mxyp1;

/* declare scalars for OpenMP code */
    int nppmx, nppmx0, nbmaxp, ntmaxp, npbm, irc;
    int nvpp;

/* declare arrays for standard code */
    float *part = NULL;
    float *qe = NULL;
    float *cue = NULL, *fxyze = NULL, *bxyze = NULL;
    float complex *exyz = NULL, *bxyz = NULL;
    float complex *qt = NULL;

```

```

float complex *cut = NULL, *fxyt = NULL, *bxyt = NULL;
float complex *ffc = NULL;
int *mixup = NULL;
float complex *sct = NULL;
float wtot[7], work[7];

/* declare arrays for MPI code */
float complex *bs = NULL, *br = NULL;
float *sbuf1 = NULL, *sbuf2 = NULL, *rbuf1 = NULL, *rbuf2 = NULL;
float *edges = NULL;
float *scs = NULL, *scr = NULL;

/* declare arrays for OpenMP code */
float *ppart = NULL, *ppbuff = NULL;
int *kp1c = NULL;
int *ncl = NULL, *iholep = NULL;
int *ncl1 = NULL, *ncl2 = NULL, *mcl1 = NULL, *mcl2 = NULL;

/* declare and initialize timing data */
float time;
struct timeval itime;
float tdpst = 0.0, tguard = 0.0, ttp = 0.0, tfield = 0.0;
float tdjpost = 0.0, tpush = 0.0, tsort = 0.0, tmov = 0.0;
float tfft[2] = {0.0,0.0};
double dtime;

irc = 0;
/* nvpp = number of shared memory nodes (0=default) */
nvpp = 0;
/* printf("enter number of nodes:\n"); */
/* scanf("%i",&nvpp); */
/* initialize for shared memory parallel processing */
cinit_omp(nvpp);

/* initialize scalars for standard code */
np = (double) npx*(double) npy;
nx = 1L<<indx; ny = 1L<<indy; nxh = nx/2; nyh = ny/2;
nxe = nx + 2; nye = ny + 2; nxeh = nxe/2; nnxe = ndim*nxe;
nxyh = (nx > ny ? nx : ny)/2; nxhy = nxh > ny ? nxh : ny;
mx1 = (nx - 1)/mx + 1;
nloop = tend/dt + .0001; ntime = 0;
qbme = qme;
affp = (double) nx*(double) ny/np;
dth = 0.0;

/* nvp = number of distributed memory nodes */
/* initialize for distributed memory parallel processing */
cppinit2(&idproc,&nvp,argc,argv);
kstrt = idproc + 1;
/* check if too many processors */
if (nvp > ny) {
    if (kstrt==1) {
        printf("Too many processors requested: ny, nvp=%d,%d\n",ny,nvp);
    }
}

```

```

        goto L3000;
    }

/* initialize data for MPI code */
edges = (float *) malloc(idps*sizeof(float));
/* calculate partition variables: edges, nyp, noff, nypmx */
/* edges[0:1] = lower:upper boundary of particle partition */
/* nyp = number of primary (complete) gridpoints in particle partition */
/* noff = lowermost global gridpoint in particle partition */
/* nypmx = maximum size of particle partition, including guard cells */
/* nypmn = minimum value of nyp */
cpdicomp2l(edges,&nyp,&noff,&nypmx,&nypmn,ny,kstrt,nvp,idps);
if (nypmn < 1) {
    if (kstrt==1) {
        printf("combination not supported nvp, ny =%d,%d\n",ny,nvp);
    }
    goto L3000;
}

/* initialize additional scalars for MPI code */
/* kxp = number of complex grids in each field partition in x direction */
kxp = (nxh - 1)/nvp + 1;
/* kyp = number of complex grids in each field partition in y direction */
kyp = (ny - 1)/nvp + 1;
/* npmax = maximum number of electrons in each partition */
npmax = (np/nvp)*1.25;
/* mypl = number of tiles in y direction */
mypl = (nyp - 1)/my + 1; mxyp1 = mx1*mypl;

/* allocate and initialize data for standard code */
part = (float *) malloc(idimp*npmax*sizeof(float));
qe = (float *) malloc(nxe*nypmx*sizeof(float));
fxyze = (float *) malloc(ndim*nxe*nypmx*sizeof(float));
cue = (float *) malloc(ndim*nxe*nypmx*sizeof(float));
bxyze = (float *) malloc(ndim*nxe*nypmx*sizeof(float));
exyz = (float complex *) malloc(ndim*nye*kxp*sizeof(float complex));
bxyz = (float complex *) malloc(ndim*nye*kxp*sizeof(float complex));
qt = (float complex *) malloc(nye*kxp*sizeof(float complex));
fxyt = (float complex *) malloc(ndim*nye*kxp*sizeof(float complex));
cut = (float complex *) malloc(ndim*nye*kxp*sizeof(float complex));
bxyt = (float complex *) malloc(ndim*nye*kxp*sizeof(float complex));
ffc = (float complex *) malloc(nyh*kxp*sizeof(float complex));
mixup = (int *) malloc(nxhy*sizeof(int));
sct = (float complex *) malloc(nxyh*sizeof(float complex));
kp1c = (int *) malloc(mxyp1*sizeof(int));

/* allocate and initialize data for MPI code */
bs = (float complex *) malloc(ndim*kxp*kyp*sizeof(float complex));
br = (float complex *) malloc(ndim*kxp*kyp*sizeof(float complex));
scs = (float *) malloc(nxe*2*sizeof(float));
scr = (float *) malloc(ndim*nxe*sizeof(float));

/* prepare fft tables */
cwpfft2rinit(mixup,sct,indx,indy,nxhy,nxyh);

```

```

/* calculate form factors */
    isign = 0;
    cmppois23(qt, fxyt, isign, ffc, ax, ay, affp, &we, nx, ny, kstrt, nye, kxp, nyh);
/* initialize electrons */
    nps = 1;
    npp = 0;
    cpdistr2h(part, edges, &npp, nps, vtx, vty, vtz, vx0, vy0, vz0, npx, npy, nx, ny,
               idimp, npmax, idps, ipbc, &ierr);
/* check for particle initialization error */
    if (ierr != 0) {
        if (kstrt==1) {
            printf("particle initialization error: ierr=%d\n", ierr);
        }
        goto L3000;
    }

/* initialize transverse electromagnetic fields */
    for (j = 0; j < ndim*nye*kxp; j++) {
        exyz[j] = 0.0 + 0.0*_Complex_I;
        bxyz[j] = 0.0 + 0.0*_Complex_I;
    }

/* find number of particles in each of mx, my tiles: updates kplic, nppmx */
    cppdblkp2l(part, kplic, npp, noff, &nppmx, idimp, npmax, mx, my, mx1, mxyp1,
               &irc);
    if (irc != 0) {
        printf("%d, cppdblkp2l error, irc=%d\n", kstrt, irc);
        cppabort();
        exit(1);
    }

/* allocate vector particle data */
    nppmx0 = (1.0 + xtras)*nppmx;
    ntmaxp = xtras*nppmx;
    npbmx = xtras*nppmx;
    nbmaxp = 0.25*mx1*npbmx;
    sbufl = (float *) malloc(idimp*nbmaxp*sizeof(float));
    sbufr = (float *) malloc(idimp*nbmaxp*sizeof(float));
    rbufl = (float *) malloc(idimp*nbmaxp*sizeof(float));
    rbufr = (float *) malloc(idimp*nbmaxp*sizeof(float));
    ppart = (float *) malloc(idimp*nppmx0*mxyp1*sizeof(float));
    ppbuff = (float *) malloc(idimp*npbmx*mxyp1*sizeof(float));
    ncl = (int *) malloc(8*mxyp1*sizeof(int));
    iholep = (int *) malloc(2*(ntmaxp+1)*mxyp1*sizeof(int));
    ncll = (int *) malloc(3*mxyp1*sizeof(int));
    nclr = (int *) malloc(3*mxyp1*sizeof(int));
    mcll = (int *) malloc(3*mxyp1*sizeof(int));
    mclr = (int *) malloc(3*mxyp1*sizeof(int));

/* copy ordered particle data for OpenMP */
    cpppmovin2l(part, ppart, kplic, npp, noff, nppmx0, idimp, npmax, mx, my, mx1,
               mxyp1, &irc);
    if (irc != 0) {
        printf("%d, cpppmovin2l overflow error, irc=%d\n", kstrt, irc);
        cppabort();
    }

```

```

        exit(1);
    }
/* sanity check */
cpppcheck2l(ppart,kpic,noff,nyp,idimp,nppmx0,nx,mx,my,mx1,mypl,&irc);
if (irc != 0) {
    printf("%d,cpppcheck2l error: irc=%d\n",kstrt,irc);
    cppabort();
    exit(1);
}

if (dt > 0.45*ci) {
    if (kstrt==1) {
        printf("Warning: Courant condition may be exceeded!\n");
    }
}

/* * * * start main iteration loop * * * */

L500: if (nloop <= ntime)
    goto L2000;
/*    if (kstrt==1) printf("ntime = %i\n",ntime); */

/* deposit current with standard procedure: updates part, cue, ihole */
dtimer(&dtime,&itime,-1);
for (j = 0; j < ndim*nxe*nypmx; j++) {
    cue[j] = 0.0;
}
if (relativity==1) {
    cppgrjppostf2l(ppart,cue,kpic,ncl,iholep,noff,nyp,qme,dth,
        ci,nppmx0,idimp,nx,ny,mx,my,nxe,nypmx,mx1,
        mxypl,ntmaxp,&irc);
}
else {
    cppgjppostf2l(ppart,cue,kpic,ncl,iholep,noff,nyp,qme,dth,
        nppmx0,idimp,nx,ny,mx,my,nxe,nypmx,mx1,mxypl,
        ntmaxp,&irc);
}
dtimer(&dtime,&itime,1);
time = (float) dtime;
tdjpost += time;
if (irc != 0) {
    if (relativity==1) {
        printf("%d,cppgrjppostf2l error: irc=%d\n",kstrt,irc);
    }
    else {
        printf("%d,cppgjppostf2l error: irc=%d\n",kstrt,irc);
    }
    cppabort();
    exit(1);
}

/* reorder particles by tile with OpenMP */
/* first part of particle reorder on x and y cell with mx, my tiles: */
/* updates ppart, ppbuff, ncl, iholep, irc, sbuf1, sbuf, ncl1, nclr */

```

```

    dtimer(&dtime,&itime,-1);
    cppporderf2la(ppart,ppbuff,sbuf1,sbuf2,ncl,iholep,ncl1,ncl2,
        idimp,nppmx0,mx1,my1,npbm,ntmax,nbmax,&irc);
    dtimer(&dtime,&itime,1);
    time = (float) dtime;
    tsort += time;
    if (irc != 0) {
        printf("%d, cppporderf2la error:ntmax,irc=%d,%d\n",kstrt,
            ntmax,irc);
        cppabort();
        exit(1);
    }
/* move particles into appropriate spatial regions: */
/* updates rbuf2, rbuf1, mcl1, mcl2 */
    dtimer(&dtime,&itime,-1);
    cpppmove2(sbuf2,sbuf1,rbuf2,rbuf1,ncl1,ncl2,mcl1,mcl2,kstrt,nvp,
        idimp,nbmax,mx1);
    dtimer(&dtime,&itime,1);
    time = (float) dtime;
    tmov += time;
/* second part of particle reorder on x and y cell with mx, my tiles: */
/* updates ppart, kp1c */
    dtimer(&dtime,&itime,-1);
    cppporder2lb(ppart,ppbuff,rbuf1,rbuf2,kp1c,ncl,iholep,mcl1,mcl2,
        idimp,nppmx0,mx1,my1,npbm,ntmax,nbmax,&irc);
    dtimer(&dtime,&itime,1);
    time = (float) dtime;
    tsort += time;
    if (irc != 0) {
        printf("%d, cppporder2lb error:nppmx0,irc=%d,%d\n",kstrt,nppmx0,
            irc);
        cppabort();
        exit(1);
    }
}

/* deposit charge with standard procedure: updates qe */
    dtimer(&dtime,&itime,-1);
    for (j = 0; j < nxe*nypmx; j++) {
        qe[j] = 0.0;
    }
    cppgppost2l(ppart,qe,kp1c,noff,qme,idimp,nppmx0,mx,my,nxe,nypmx,
        mx1,myp1);
    dtimer(&dtime,&itime,1);
    time = (float) dtime;
    tdpost += time;

/* add guard cells with standard procedure: updates cue, qe */
    dtimer(&dtime,&itime,-1);
    cppacguard2xl(cue,nyp,nx,ndim,nxe,nypmx);
    cppnacguard2l(cue,scr,nyp,nx,ndim,kstrt,nvp,nxe,nypmx);
    cppaguard2xl(qe,nyp,nx,nxe,nypmx);
    cppnaguard2l(qe,scr,nyp,nx,kstrt,nvp,nxe,nypmx);
    dtimer(&dtime,&itime,1);
    time = (float) dtime;

```

```

    tguard += time;

/* transform charge to fourier space with standard procedure: updates qt */
/* modifies qe */
    dtimer(&dtype,&itime,-1);
    isign = -1;
    cwppfft2rm((float complex *)qe,qt,bs,br,isign,ntpose,mixup,sct,&ttp,
               indx,indy,kstrt,nvp,nxeh,nye,kxp,kyp,nypmx,nxhy,nxyh);
    dtimer(&dtype,&itime,1);
    time = (float) dtype;
    tfft[0] += time;
    tfft[1] += ttp;

/* transform current to fourier space with standard procedure: updates cut */
/* modifies cue */
    dtimer(&dtype,&itime,-1);
    isign = -1;
    cwppfft2rm3((float complex *)cue,cut,bs,br,isign,ntpose,mixup,sct,
               &ttp,indx,indy,kstrt,nvp,nxeh,nye,kxp,kyp,nypmx,nxhy,
               nxyh);
    dtimer(&dtype,&itime,1);
    time = (float) dtype;
    tfft[0] += time;
    tfft[1] += ttp;

/* take transverse part of current with standard procedure: updates cut */
/* modifies cue */
    dtimer(&dtype,&itime,-1);
    cmppcuperp2(cut,nx,ny,kstrt,nye,kxp);
    dtimer(&dtype,&itime,1);
    time = (float) dtype;
    tfield += time;

/* calculate electromagnetic fields in fourier space with standard */
/* procedure: updates exyz, bxyz */
    dtimer(&dtype,&itime,-1);
    if (ntime==0) {
        cmippbpoisp23(cut,bxyz,ffc,ci,&wm,nx,ny,kstrt,nye,kxp,nyh);
        wf = 0.0;
        dth = 0.5*dt;
    }
    else {
        cmppmaxwel2(exyz,bxyz,cut,ffc,affp,ci,dt,&wf,&wm,nx,ny,kstrt,
                   nye,kxp,nyh);
    }
    dtimer(&dtype,&itime,1);
    time = (float) dtype;
    tfield += time;

/* calculate force/charge in fourier space with standard procedure: */
/* updates fxyt */
    dtimer(&dtype,&itime,-1);
    isign = -1;
    cmppois23(qt,fxyt,isign,ffc,ax,ay,affp,&we,nx,ny,kstrt,nye,kxp,

```

```

        nyh);
    dtimer(&dtype,&itime,1);
    time = (float) dtype;
    tfield += time;

/* add longitudinal and transverse electric fields with standard */
/* procedure: updates fxyt */
    dtimer(&dtype,&itime,-1);
    isign = 1;
    cmppemfield2(fxyt,exyz,ffc,isign,nx,ny,kstrt,nye,kxp,nyh);
/* copy magnetic field with standard procedure: updates bxyt */
    isign = -1;
    cmppemfield2(bxyt,bxyz,ffc,isign,nx,ny,kstrt,nye,kxp,nyh);
    dtimer(&dtype,&itime,1);
    time = (float) dtype;
    tfield += time;

/* transform force to real space with standard procedure: updates fxyze */
/* modifies fxyt */
    dtimer(&dtype,&itime,-1);
    isign = 1;
    cwppfft2rm3((float complex *)fxyze,fxyt,bs,br,isign,ntpose,mixup,
                sct,&ttp,indx,indy,kstrt,nvp,nxeh,nye,kxp,kyp,nypmx,
                nxhy,nxyh);
    dtimer(&dtype,&itime,1);
    time = (float) dtype;
    tfft[0] += time;
    tfft[1] += ttp;

/* transform magnetic field to real space with standard procedure: */
/* updates bxyze, modifies bxyt */
    dtimer(&dtype,&itime,-1);
    isign = 1;
    cwppfft2rm3((float complex *)bxyze,bxyt,bs,br,isign,ntpose,mixup,
                sct,&ttp,indx,indy,kstrt,nvp,nxeh,nye,kxp,kyp,nypmx,
                nxhy,nxyh);
    dtimer(&dtype,&itime,1);
    time = (float) dtype;
    tfft[0] += time;
    tfft[1] += ttp;

/* copy guard cells with standard procedure: updates fxyze, bxyze */
    dtimer(&dtype,&itime,-1);
    cppncguard2l(fxyze,nyp,kstrt,nvp,nxe,nypmx);
    cppcguard2xl(fxyze,nyp,nx,ndim,nxe,nypmx);
    cppncguard2l(bxyze,nyp,kstrt,nvp,nxe,nypmx);
    cppcguard2xl(bxyze,nyp,nx,ndim,nxe,nypmx);
    dtimer(&dtype,&itime,1);
    time = (float) dtype;
    tguard += time;

/* push particles: updates part, wke, and ihole */
    dtimer(&dtype,&itime,-1);
    wke = 0.0;

```



```

    if (relativity==1) {
        cppgrbpushf231(ppart, fxyze, bxyze, kplic, ncl, iholep, noff, nyp,
                      qbme, dt, dth, ci, &wke, idimp, nppmx0, nx, ny, mx, my,
                      nxe, nypmx, mx1, my1, ntmaxp, &irc);
    }
    else {
        cppgbpushf231(ppart, fxyze, bxyze, kplic, ncl, iholep, noff, nyp, qbme,
                      dt, dth, &wke, idimp, nppmx0, nx, ny, mx, my, nxe, nypmx,
                      mx1, my1, ntmaxp, &irc);
    }
    dtimer(&dtype, &itime, 1);
    time = (float) dtype;
    tpush += time;
    if (irc != 0) {
        if (relativity==1) {
            printf("%d, cppgrbpushf231 error: irc=%d\n", kstrt, irc);
        }
        else {
            printf("%d, cppgbpushf231 error: irc=%d\n", kstrt, irc);
        }
        cppabort();
        exit(1);
    }
}

/* reorder particles by tile with OpenMP */
/* first part of particle reorder on x and y cell with mx, my tiles: */
/* updates ppart, ppbuff, ncl, iholep, irc, sbuf1, sbuf2, ncl1, ncl2 */
    dtimer(&dtype, &itime, -1);
    cppporderf2la(ppart, ppbuff, sbuf1, sbuf2, ncl, iholep, ncl1, ncl2,
                  idimp, nppmx0, mx1, my1, npbm, ntmaxp, nbmaxp, &irc);
    dtimer(&dtype, &itime, 1);
    time = (float) dtype;
    tsort += time;
    if (irc != 0) {
        printf("%d, cppporderf2la error: ntmaxp, irc=%d, %d\n", kstrt,
              ntmaxp, irc);
        cppabort();
        exit(1);
    }
}

/* move particles into appropriate spatial regions: */
/* updates rbuf1, rbuf2, mcl1, mcl2 */
    dtimer(&dtype, &itime, -1);
    cpppmove2(sbuf1, sbuf2, rbuf1, rbuf2, ncl1, ncl2, mcl1, mcl2, kstrt, nvp,
              idimp, nbmaxp, mx1);
    dtimer(&dtype, &itime, 1);
    time = (float) dtype;
    tmov += time;

/* second part of particle reorder on x and y cell with mx, my tiles: */
/* updates ppart, kplic */
    dtimer(&dtype, &itime, -1);
    cppporder2lb(ppart, ppbuff, rbuf1, rbuf2, kplic, ncl, iholep, mcl1, mcl2,
                  idimp, nppmx0, mx1, my1, npbm, ntmaxp, nbmaxp, &irc);
    dtimer(&dtype, &itime, 1);
    time = (float) dtype;

```

```

        tsort += time;
        if (irc != 0) {
            printf("%d,cppporder2lb error:nppmx0,irc=%d,%d\n",kstrt,nppmx0,
                irc);
            cppabort();
            exit(1);
        }

/* energy diagnostic */
    wt = we + wf + wm;
    wtot[0] = wt;
    wtot[1] = wke;
    wtot[2] = 0.0;
    wtot[3] = wke + wt;
    wtot[4] = we;
    wtot[5] = wf;
    wtot[6] = wm;
    cppsum(wtot,work,7);
    wke = wtot[1];
    we = wtot[4];
    wf = wtot[5];
    wm = wtot[6];
    if (ntime==0) {
        if (kstrt==1) {
            wt = we + wf + wm;
            printf("Initial Total Field, Kinetic and Total Energies:\n");
            printf("%e %e %e\n",wt,wke,wke+wt);
            printf("Initial Electrostatic, Transverse Electric and \
Magnetic Field Energies:\n");
            printf("%e %e %e\n",we,wf,wm);
        }
    }
    ntime += 1;
    goto L500;
L2000:

/* * * * end main iteration loop * * * */

    if (kstrt==1) {
        printf("ntime, relativity = %i,%i\n",ntime,relativity);
        printf("MPI nodes nvp = %i\n",nvp);
        wt = we + wf + wm;
        printf("Final Total Field, Kinetic and Total Energies:\n");
        printf("%e %e %e\n",wt,wke,wke+wt);
        printf("Final Electrostatic, Transverse Electric and Magnetic \
Field Energies:\n");
        printf("%e %e %e\n",we,wf,wm);

        printf("\n");
        printf("deposit time = %f\n",tdpost);
        printf("current deposit time = %f\n",tdjpost);
        tdpost += tdjpost;
        printf("total deposit time = %f\n",tdpost);
        printf("guard time = %f\n",tguard);
    }

```

```

    printf("solver time = %f\n",tfield);
    printf("fft and transpose time = %f,%f\n",tfft[0],tfft[1]);
    printf("push time = %f\n",tpush);
    printf("particle move time = %f\n",tmov);
    printf("sort time = %f\n",tsort);
    tfield += tguard + tfft[0];
    printf("total solver time = %f\n",tfield);
    time = tdpost + tpush + tmov + tsort;
    printf("total particle time = %f\n",time);
    wt = time + tfield;
    printf("total time = %f\n",wt);
    printf("\n");

    wt = 1.0e+09/(((float) nloop)*((float) np));
    printf("Push Time (nsec) = %f\n",tpush*wt);
    printf("Deposit Time (nsec) = %f\n",tdpost*wt);
    printf("Sort Time (nsec) = %f\n",tsort*wt);
    printf("Total Particle Time (nsec) = %f\n",time*wt);
}

L3000:
    cppexit();
    return 0;
}

```