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C-----
      subroutine VGPUSH2LT(part,fx,y,qbm,dt,ek,idimp,nop,npe,nx,ny,nxv,
      lnyv,ipbc)
c for 2d code, this subroutine updates particle co-ordinates and
c velocities using leap-frog scheme in time and first-order linear
c interpolation in space, with various boundary conditions.
c vectorizable version using guard cells
c 44 flops/particle, 12 loads, 4 stores
c input: all, output: part, ek
c equations used are:
c  $vx(t+dt/2) = vx(t-dt/2) + (q/m)*fx(x(t),y(t))*dt,$ 
c  $vy(t+dt/2) = vy(t-dt/2) + (q/m)*fy(x(t),y(t))*dt,$ 
c where  $q/m$  is charge/mass, and
c  $x(t+dt) = x(t) + vx(t+dt/2)*dt,$   $y(t+dt) = y(t) + vy(t+dt/2)*dt$ 
c  $fx(x(t),y(t))$  and  $fy(x(t),y(t))$  are approximated by interpolation from
c the nearest grid points:
c  $fx(x,y) = (1-dy)*((1-dx)*fx(n,m)+dx*fx(n+1,m)) + dy*((1-dx)*fx(n,m+1)$ 
c  $+ dx*fx(n+1,m+1))$ 
c  $fy(x,y) = (1-dy)*((1-dx)*fy(n,m)+dx*fy(n+1,m)) + dy*((1-dx)*fy(n,m+1)$ 
c  $+ dx*fy(n+1,m+1))$ 
c where  $n,m$  = leftmost grid points and  $dx = x-n,$   $dy = y-m$ 
c part(n,1) = position x of particle n
c part(n,2) = position y of particle n
c part(n,3) = velocity vx of particle n
c part(n,4) = velocity vy of particle n
c  $fx(1,j,k)$  = x component of force/charge at grid (j,k)
c  $fy(2,j,k)$  = y component of force/charge at grid (j,k)
c that is, convolution of electric field over particle shape
c qbm = particle charge/mass
c dt = time interval between successive calculations
c kinetic energy/mass at time t is also calculated, using
c  $ek = .125*sum((vx(t+dt/2)+vx(t-dt/2))^2+(vy(t+dt/2)+vy(t-dt/2))^2)$ 
c idimp = size of phase space = 4
c nop = number of particles
c npe = first dimension of particle array
c nx/ny = system length in x/y direction
c nxv = second dimension of field array, must be  $\geq nx+1$ 
c nyv = third dimension of field array, must be  $\geq ny+1$ 
c ipbc = particle boundary condition = (0,1,2,3) =
c (none,2d periodic,2d reflecting,mixed reflecting/periodic)
      implicit none
      integer idimp, nop, npe, nx, ny, nxv, nyv, ipbc
      real qbm, dt, ek
      real part, fxy
      dimension part(npe,idimp), fxy(2,nxv*nyv)
c local data
      integer npblk, lvect
      parameter(npblk=32,lvect=4)
      integer i, j, k, ipp, joff, nps, nn, mm
      real qtm, edgelx, edgely, edgerx, edgery, dxp, dyp, amx, amy
      real x, y, dx, dy, vx, vy
c scratch arrays
      integer n
      real s, t

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    dimension n(npblk), s(npblk,lvect), t(npblk,2)
    double precision sum1
    qtm = qbm*dt
    sum1 = 0.0d0
c set boundary values
    edgelx = 0.0
    edgely = 0.0
    edgerx = real(nx)
    edgery = real(ny)
    if (ipbc.eq.2) then
        edgelx = 1.0
        edgely = 1.0
        edgerx = real(nx-1)
        edgery = real(ny-1)
    else if (ipbc.eq.3) then
        edgelx = 1.0
        edgerx = real(nx-1)
    endif
    ipp = nop/npblk
c outer loop over number of full blocks
    do 60 k = 1, ipp
        joff = npblk*(k - 1)
c inner loop over particles in block
        do 10 j = 1, npblk
c find interpolation weights
            x = part(j+joff,1)
            y = part(j+joff,2)
            nn = x
            mm = y
            dxp = x - real(nn)
            dyp = y - real(mm)
            n(j) = nn + nxv*mm
            amx = 1.0 - dxp
            amy = 1.0 - dyp
            s(j,1) = amx*amy
            s(j,2) = dxp*amy
            s(j,3) = amx*dyp
            s(j,4) = dxp*dyp
            t(j,1) = x
            t(j,2) = y
        10 continue
c find acceleration
        do 30 j = 1, npblk
            nn = n(j)
            mm = nn + nxv - 2
            dx = 0.0
            dy = 0.0
!dir$ ivdep
            do 20 i = 1, lvect
                if (i.gt.2) nn = mm
                dx = dx + fxy(1,i+nn)*s(j,i)
                dy = dy + fxy(2,i+nn)*s(j,i)
            20 continue
            s(j,1) = dx

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        s(j,2) = dy
    30 continue
c new velocity
    do 40 j = 1, npblk
        x = t(j,1)
        y = t(j,2)
        dxp = part(j+joff,3)
        dyp = part(j+joff,4)
        vx = dxp + qtm*s(j,1)
        vy = dyp + qtm*s(j,2)
c average kinetic energy
        dxp = dxp + vx
        dyp = dyp + vy
        sum1 = sum1 + (dxp*dxp + dyp*dyp)
c new position
        s(j,1) = x + vx*dt
        s(j,2) = y + vy*dt
        s(j,3) = vx
        s(j,4) = vy
    40 continue
! check boundary conditions
!dir$ novector
    do 50 j = 1, npblk
        dx = s(j,1)
        dy = s(j,2)
        vx = s(j,3)
        vy = s(j,4)
c periodic boundary conditions
        if (ipbc.eq.1) then
            if (dx.lt.edgelx) dx = dx + edgerx
            if (dx.ge.edgerx) dx = dx - edgerx
            if (dy.lt.edgely) dy = dy + edgery
            if (dy.ge.edgery) dy = dy - edgery
c reflecting boundary conditions
        else if (ipbc.eq.2) then
            if ((dx.lt.edgelx).or.(dx.ge.edgerx)) then
                dx = t(j,1)
                vx = -vx
            endif
            if ((dy.lt.edgely).or.(dy.ge.edgery)) then
                dy = t(j,2)
                vy = -vy
            endif
c mixed reflecting/periodic boundary conditions
        else if (ipbc.eq.3) then
            if ((dx.lt.edgelx).or.(dx.ge.edgerx)) then
                dx = t(j,1)
                vx = -vx
            endif
            if (dy.lt.edgely) dy = dy + edgery
            if (dy.ge.edgery) dy = dy - edgery
        endif
c set new position
        part(j+joff,1) = dx

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        part(j+joff,2) = dy
c set new velocity
        part(j+joff,3) = vx
        part(j+joff,4) = vy
    50 continue
    60 continue
        nps = npblk*ipp + 1
c loop over remaining particles
        do 70 j = nps, nop
c find interpolation weights
            x = part(j,1)
            y = part(j,2)
            nn = x
            mm = y
            dxp = x - real(nn)
            dyp = y - real(mm)
            nn = nn + nxv*mm + 1
            amx = 1.0 - dxp
            amy = 1.0 - dyp
c find acceleration
            dx = amx*fxy(1,nn)
            dy = amx*fxy(2,nn)
            dx = amy*(dxp*fxy(1,nn+1) + dx)
            dy = amy*(dyp*fxy(2,nn+1) + dy)
            vx = amx*fxy(1,nn+nxv)
            vy = amx*fxy(2,nn+nxv)
            dx = dx + dyp*(dxp*fxy(1,nn+1+nxv) + vx)
            dy = dy + dyp*(dyp*fxy(2,nn+1+nxv) + vy)
c new velocity
            dxp = part(j,3)
            dyp = part(j,4)
            vx = dxp + qtm*dx
            vy = dyp + qtm*dy
c average kinetic energy
            dxp = dxp + vx
            dyp = dyp + vy
            sum1 = sum1 + (dxp*dxp + dyp*dyp)
c new position
            dx = x + vx*dt
            dy = y + vy*dt
c periodic boundary conditions
            if (ipbc.eq.1) then
                if (dx.lt.edgelx) dx = dx + edgerx
                if (dx.ge.edgerx) dx = dx - edgerx
                if (dy.lt.edgely) dy = dy + edgery
                if (dy.ge.edgery) dy = dy - edgery
c reflecting boundary conditions
            else if (ipbc.eq.2) then
                if ((dx.lt.edgelx).or.(dx.ge.edgerx)) then
                    dx = x
                    vx = -vx
                endif
                if ((dy.lt.edgely).or.(dy.ge.edgery)) then
                    dy = y

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        vy = -vy
    endif
c mixed reflecting/periodic boundary conditions
    else if (ipbc.eq.3) then
        if ((dx.lt.edgex).or.(dx.ge.edgerx)) then
            dx = x
            vx = -vx
        endif
        if (dy.lt.edgely) dy = dy + edgery
        if (dy.ge.edgery) dy = dy - edgery
    endif
c set new position
    part(j,1) = dx
    part(j,2) = dy
c set new velocity
    part(j,3) = vx
    part(j,4) = vy
    70 continue
c normalize kinetic energy
    ek = ek + 0.125*sum1
    return
end

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C-----
      subroutine VGPOST2LT(part,q,qm,nop,npe,idimp,nxv,nyv)
C for 2d code, this subroutine calculates particle charge density
C using first-order linear interpolation, periodic boundaries
C vectorizable version using guard cells
C 17 flops/particle, 6 loads, 4 stores
C input: all, output: q
C charge density is approximated by values at the nearest grid points
C q(n,m)=qm*(1.-dx)*(1.-dy)
C q(n+1,m)=qm*dx*(1.-dy)
C q(n,m+1)=qm*(1.-dx)*dy
C q(n+1,m+1)=qm*dx*dy
C where n,m = leftmost grid points and dx = x-n, dy = y-m
C part(n,1) = position x of particle n
C part(n,2) = position y of particle n
C q(j,k) = charge density at grid point j,k
C qm = charge on particle, in units of e
C nop = number of particles
C npe = first dimension of particle array
C idimp = size of phase space = 4
C nxv = first dimension of charge array, must be >= nx+1
C nyv = second dimension of charge array, must be >= ny+1
      implicit none
      integer nop, npe, idimp, nxv, nyv
      real qm
      real part, q
      dimension part(npe,idimp), q(nxv*nyv)
C local data
      integer npblk, lvect
      parameter(npblk=32,lvect=4)
      integer i, j, k, ipp, joff, nps, nn, mm
      real x, y, dxp, dyp, amx, amy
C scratch arrays
      integer n
      real s
      dimension n(npblk), s(npblk,lvect)
      ipp = nop/npblk
C outer loop over number of full blocks
      do 40 k = 1, ipp
        joff = npblk*(k - 1)
C inner loop over particles in block
        do 10 j = 1, npblk
C find interpolation weights
          x = part(j+joff,1)
          y = part(j+joff,2)
          nn = x
          mm = y
          dxp = qm*(x - real(nn))
          dyp = y - real(mm)
          n(j) = nn + nxv*mm
          amx = qm - dxp
          amy = 1.0 - dyp
          s(j,1) = amx*amy
          s(j,2) = dxp*amy
        enddo
      enddo

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        s(j,3) = amx*dyp
        s(j,4) = dxp*dyp
    10 continue
c deposit charge
    do 30 j = 1, npblk
        nn = n(j)
        mm = nn + nxv - 2
!dir$ ivdep
        do 20 i = 1, lvect
            if (i.gt.2) nn = mm
            q(i+nn) = q(i+nn) + s(j,i)
        20 continue
    30 continue
    40 continue
        nps = npblk*ipp + 1
c loop over remaining particles
    do 50 j = nps, nop
c find interpolation weights
        x = part(j,1)
        y = part(j,2)
        nn = x
        mm = y
        dxp = qm*(x - real(nn))
        dyp = y - real(mm)
        nn = nn + nxv*mm + 1
        amx = qm - dxp
        amy = 1.0 - dyp
c deposit charge
        x = q(nn) + amx*amy
        y = q(nn+1) + dxp*amy
        q(nn) = x
        q(nn+1) = y
        x = q(nn+nxv) + amx*dyp
        y = q(nn+nxv+1) + dxp*dyp
        q(nn+nxv) = x
        q(nn+nxv+1) = y
    50 continue
    return
end

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